/sem-I(cBSGS)/Inst & control/Appliced linear Algebra May'-2016

QP Code: 14402

(3 Hours)

[Total Marks: 80

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- Question No. 1 is compulsory.
- Answer any three from the remaining five questions.
- Assume suitable data if necessary and justify the same.
- ires to the right indicate the marks

	Fig	gures to the right indicate the marks.	
1	Bri	efly explain the following:-	20
	a	Minimal Polynomial and Characteristic polynomial.	
	b	Inner product and Cross product of vectors.	
	c	Algebraic and Geometric multiplicities of eigen value.	
	d	Column space and Null space.	
2 .	a	Explain the concept of Linear independence of vectors. Find the values of 'x' such that	10
		the vectors $(1\ 2\ 1)$, $(x, 3, 1)$ and $(2, x, 0)$ are linearly dependent.	
	b	What is meant by Linear transformation? Define Kernel and range as applied to linear	10
		transformation.	
3	a	Prove Cayley Hamilton Theorem.	10
	b	What is orthogonal Vector? Extend (2, 3,-1), (1, -2,-4) to an orthogonal basis of R ³ .	10
4	a	Explain the concept of Vector space, Basis, Span and Dimension.	10
	b	Investigate for what values of ' λ ' and ' μ ', the equations $x+y+z=6$, $x+2y+3z=10$ and	10
		$x+2y+\lambda z=\mu$ have a unique solution.	
=	a	Explain Singular value Decomposition and its application. Find the Singular values of	10
3	a		
		the matrix $A = \begin{bmatrix} 4 & 0 \\ 3 & -5 \end{bmatrix}$	
	b	Explain Row Echelon form. Find the row- reduced echelon form of the matrix	10
		$A = \begin{bmatrix} 0 & -1 & 2 & 0 \\ 2 & 2 & 1 & 5 \\ 1 & 2 & 1 & 5 \end{bmatrix}$ and hence find its rank.	
		$\begin{bmatrix} 1 & 3 & -1 & 0 \end{bmatrix}$ and hence find its rank.	
6	a	Write short note on Gram Schmidt process of orthogonalization.	10
	1.	Define eigen values and eigen vectors of a matrix. Compute all the eigen values and	.10
	р	Delvic eigen values and eigen vectors of a matrix. Compare an ano eigen values	

eigen vectors of $A = \begin{bmatrix} 8 & 4 \\ 2 & 6 \end{bmatrix}$ and comment whether A is diagonalizable or not.

M.E. SEMI Advanced Senson & Signal (CBSGT)

(INST & CONTROL)

QP Code: 14406 MAY

MARKS-80 Instructions:

TIME 3 hrs.

1)	Question no. 1 is compulsory.	
2)	Attempt any Three out of remaining questions.	

3) Assume suitable data wherev	er required.

Q.1)	Answer the following—	72	
a)	Explain dark current compensation for photodiodes.	20,160	(05)
b)	Discuss dissipation constant of RTD.	25	(05)

c)	State true/false and justify the same	(05)
	Resolution is limited in case of wire wound potentiometers.	
d)	Explain the use of charge sensitive amplifier	(05)

		6	
Q.2a)	Explain signal processing of inductive sensors.	.00	(10)

b)	Describe a Kelvin sensing system	with	6-wire voltage	driven	bridge	using single	(10)
	resistance transducer element.		73,				

03 a)	Explain how direction and velocity can be measured with encoders.	(10)

b)	Explain DC to DC converter for transducer signal processing system.	(10)

Q.4 a)	List the noise sources introduced at different stages of measurement system	(10)
	and suggest remedy.	

b)	Explain architecture of smart transducer with its advantages.	(10)
DI	Explain architecture of smart transducer with its advantages.	(10)

Q.5 a)	Discuss the need of guardin	g techniques used for processing signal	(10)
	from transducers with high	output impedance. Describe various	
	techniques		

			1. 1 (10)	
1-1	Dietimourich hoterino	operation of photoconductive and photovoltaic	diodes (III)	
13.1	DISHIPPHISH DELWCC	i operation of photoconductive and photovolune	diodes. (10)	

		99900
0.6)	Write short notes:	(20)
	a) Fabrication process of microsensors	

b) Accelerometers.

BB-Con. 9135-16.

M.E. - INST (CBSGS) SEM I

QP Code: 14409

CONTROL (3 Hours)

[Total Marks: 80]

N. B.:	(1)	Question	No.	1	is	compulsory.
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- (2) Attempt any four questions from remaining six questions.
- (3) Assume suitable data if necessary.
- (4) Figures to the right indicate full marks.

1. Answer the following:

- (a) Differentiate between MIAC and MRAC.
- (b) Obtain discrete time process model for a system with y(s)=g(s).u(s) where y(t) is output and u(t) is input.
- (c) What is system identification?
- (d) Explain cancellation controller.
- 2. (a) Explain any two methods of DC value estimation.

10

(b) Describe the characteristics of PI,PD and PID controllers.

10

- (a) Derive the linear response of a linear system if stationary stochastic signal is applied 10 via estimation of ACF of i/p and CCF of i/p and o/p signal.
 - (b) Define MIT rule and obtain the MIT rule for feedforward gain.

10

- (a) Derive the equation for parameter estimator using non recursive LS method. (b) Write a note on dual adaptive controllers.
 - 10 10
- (a) What are the various methods of building deterministic state controller? Draw the general adaptive state controller scheme and briefly explain it.
 - 10

(b) Explain dead beat controller.

10

6. Write short notes on: 20

(a) Square root filtering

- (b) Minimum variance control
- (c) Tuning of controllers.

BB-Con. 9668-16.

Sem-I CCBsas) / Inst & cont / Bio-Inst & Imaging / May-16.

Q.P. Code: 14412

		(3 Hours) [Total Marks:	80
N.	В. :	(1) Question No.1 is compulsory.	CT P
		(2) Answer any Three from the remaining Five questions.	7
1.		Explain the need for Sub-carriers in Bio-telemetry system. Explain the principle and working of PET imaging system. Explain need and working of Chopper Amplifier with neat diagram.	5 5
		Explain freed and working of Chopper Ampfiffer with heat diagram. Explain the concept behind Driven Right leg configuration.	5
2.	-	Explain working of 8—channel EEG machine with 10—20 electrode placement. Explain with a neat diagram working of SPECT scanner system.	10 10
3.	(a) (b)	What is Cardio version? Explain working of cardioverter with diagram. Explain the various techniques used for reducing noise and interference in Biomedical systems for optimal performance.	10 10
4.	(a)	What is a Retinal Implant? Explain working of different types of retinal implants with a neat diagram.	10
	(b)	Explain working of Muscle stimulators with different types of waveforms.	10
5.	(a)	Explain the working of Multichannel Radio-telemetry system with Frequency Division Multiplexing.	10
	(b)	Explain the principle and working of any one type of Isolation amplifier.	10
5	. V	Write Short Notes on (5 Marks each): (i) Electrode Electrolyte Model (ii) Telemedicine (iii) Advanced Instrumentation Amplifier (iv) Cochlear implant	20

ADV. ELEC. CIRCUITS.

QP Code: 14430

Durati	ion 3 Hours [Total Marks: 80]	
Note:	1. Question No. 1 is compulsory.	
	2. Attempt any three questions from remaining five questions.	
	3. Assume suitable data if necessary.	100
	and the second s	
Q. 1 a)	Explain clearly meaning and uses of voltage references and current references.	05
b)	Explain working of logarithmic amplifier and its applications.	05
c)	Explain the fastest method of Analog to Digital Conversion.	05
d)	Explain why separate analog and digital grounds are used in mixed signal processing.	05
Q. 2 a)	Explain working of a Millivolt Peak detect circuit with circuit diagram.	10
b	Explain working of switched capacitor low pass filter.	10
Q.3 a)	Explain working of analog multiplexer and its applications.	10
b)	Explain need of hysteresis in comparator circuit using circuit diagram.	10
Q.4 a)	Explain working of DC to DC convertor and mention its uses in signal processing.	10
b) Explain important performance parameters of Digital to Analog Convertor.	05
c)	Explain advantages of R-2R ladder network over weighted resistor network for	
	use in Digital to Analog Convertor.	05
	45	
Q.5 a)	Explain effect on performance of instrumentation amplifier due to C-R coupling	
	at its inputs and explain remedies to improve the performance.	10
b)	Discuss important issues involved in power management of electronic circuits.	10
Q.6 V	Write short notes on any two of the following -	20
a) Working of voltage to frequency convertor.	
b	RF shielding techniques.	
6	Delta Sigma technique for Analog to Digital Conversion	

BB-Con. 10418-16.