NB. Q.1 is Compulsory .	
Solve any three questions from the remaining	
Q1	20
a) Explain SCR characteristics	A. Marie
b) Write advantages of IGBT and MOSFET	0
c) Explain need of synchronizing circuit in converters)
d) Draw the circuit of Jones Chopper and explain the commutation of main SCR	* 3
· 1	112001
Q2.	20
Design a converter to give output voltage 150 V at 1A load current. The input is 230 V 50 I supply. Use UJT 2N2646.	1z ac
V_{BBmax} = 35 V for Vbb=16 V, C=0.1 μ F, \mathbb{D}_{min} =0.56 \mathcal{M}_{max} =0.75, \mathcal{M}_{type} =0.63	
lv=4mA, lp=25μA Consider temperature compensation.	
Q3 a) with the help of a neat diagram and associated waveforms discuss the operation	n of
Buck-Boost converter. Also list the advantages and disadvantages of this type of convert	
b) Explain variable frequency I.M. drive.	10
Q4	
a) Describe the working of 1phase fully controlled bridge converter in the following two modes.	
Rectifying mode	10
Inversion mode.	
Also sketch the following waveforms for $\alpha=45^{\circ}$, & $\alpha=120^{\circ}$	
h) With a short note as advation of home of the sign	
b) Write a short note on reduction of harmonic distortion.	5
c)Briefly explain the V-I characteristic of GBT.	5
Q5	
a) Explain the application of power electronics in industrial heating process.	10
 b) A 1-phase HW ac regulator feeds power to resistive load of 6Ω, from 230 V ,50 Hz source. 	10
The firing angle of SCR is $\pi/2$. Calculate	10
1) The rms value of output voltage	
2) average input current.	
Q6	
Explain the current fed ac drives & state its applications	10
State the significant features of traction drives	05
Explain any one type of forced commutation	05

Digital signal processing (CBSGS), INST, Nov/pec-2015 QP Code: 6354

(3 Hours)

[Total Marks: 80

- (1) Question No.1 is Compulsory.
 - (2) Attempt any Three questions from the remaining five questions.
 - (3) Assume suitable data if necessary.

Esswer the following (Any Four):

20

- (a) State and prove the convolution property of z-transform.
- (b) Draw the single butterfly of 2 Radix DIT & DIF FFT algorithm.
- (c) State and prove the complex conjugate property of DFT.
- (d) The transfer function of analog filter is $H(S) = \frac{S+2}{(S+1)(S+3)}$ design a digital IIR filters by means of IIT. Assume T = 0.1 Sec.
- (e) Determine IDFT of x(k) = [6, -1-j, 0]-1+j] by using DIT FFT algorithm.
- If $x_1(n) = [1, 2, 0, 3]$ and $x_2(n) = [1, 2, 3, 2]$. Find the DFT of both the sequence 10 by using DFT only once (not otherwise).
- Derive and draw the FFT for N = 6 = 2.3 using DIT FFT algorithm.
- If $x_1(n) = [1, 2, 3, 5]$ and $x_2(n) = [2, 4, 2, 3]$. Obtain $x_1(n) \otimes x_2(n)$ by using DIF 10 FFT algorithm.
- Prove the relation between the analog and digital filter by means of Bilinear 10

 Transformation Technique.
- Determine the output of a Linear FIR Filter whose impulse response $h(n) = \{3, 2, 10\}$ 1 x(n) = [1, 0, 2, 1, 0, -2, -1, 0, 3, 1] using over lap add method.
 - Determine the frequency response of the system $h(n) = a^n u(n)$ magnatude and 10 phase response of it.
- $y(n) = x(n) + \frac{1}{4}x(n-1) + \frac{1}{6}y(n-1) + \frac{1}{6}x(n-2)$ Realize the system by using Direct 10

form - 1 cascade and parallel form realization.

Design a digital Butterworth filter that satisfy the following constraint using Bilinear 10

Transformation. Assume T = 1 Sec

$$0.9 = \le \left| \mathbf{H} \left(e^{j\omega} \right) \right| \le 1 \qquad 0 \le \omega \le \frac{\pi}{2}$$
$$\left| \mathbf{H} \left(e^{j\omega} \right) \right| \le 0.2 \quad \frac{3\pi}{4} \le \omega \le \pi$$

TURN OVER

2

(a) A pass filter is to be designed which following frequency response

10

$$\operatorname{Hd}\left(e^{j\omega}\right) = e^{-j3\omega} - \frac{3\pi}{4} \le \omega \le \frac{3\pi}{4}$$
$$\frac{3\pi}{4} \le |\omega| \le \pi$$

Determine the filter coefficient h(n) by using Hamming window.

(b) A one state decimator is characterised by the following decimator factor = 3 Antialising filter coefficient

10

$$h(0) = -0.06 = h(4)$$

$$h(1) = 0.30 = h(3)$$

$$h(2) = 0.62$$

Given the data x(n) with a successive [6, -2, -3, 8, 6, 4, -2]. Calculate and list filtered output w(n) and the output of the decimator y(n).

Q.P. Code: 6396

		(3 Hours) [Total Marks:	80
			Line
Ñ.	B. :	(1) Question No. 1 is compulsory.	want 1
		(2) Attempt any three questions from question no. 2 to 6.	9
		(3) Assume suitable data if necessary.	
1.	(a)	Define embedded systems. Give examples of embedded systems. What are	5
		the types of embedded systems.	4.5
	(b)	Interface and LED to PIC18F microcontroller. Explain interfacing circuit.	5
		Write a program to blink LED.at regular interval.	
	(c)	List the features of PIC18F microcontroller.	5
	(d)	Explain priority inversion with suitable example.	5
2.	(a)	Explain Port A pin structure of PIC18F microcontroller. Write a program to	10
		configure port A & B as input and Port C and D as output.	
	(b)	Write a program to convert 8 bit binary no. to BCD.	10
			112120
3.	(a)	Explain PIC18F serial port in brief. Write a program to transmit "INSTRU"	10
		serially at 9600 bits per second. Assume suitable clock frequency.	4.0
	(b)	Interface 16 x 2 LCD module to PIC18F MCU. explain the same. Write a	10
		program to display "INSTRUMENTATION" on first line & "ENGINEERING"	
		on second line.	
		PICI OF MCII Write a program to display	10
4.	(a)	Interface four 7-segment displays to PIC18F MCU. Write a program to display	10
		"1234" on it.	10
	(b)	What is task scheduling in RTOS? Explain various task scheduling algorithms.	10
_		Explain on-chip ADC module of PIC18F MCU. Write a program to Read	10
3.	(a)	channel no.0 and display it on port B(lower byte) and port C (HB).	10
	(4)	100 TT	10
	(b)	Assume clock frequency is 16MHz.	
		Assume clock requerey is foreign.	- 10 - 10
5	(a)	Explain design challenges of Embedded system.	10
-	(h)	Write a short note on (any two)	10
	(0)	(i) I ² C communication protocol	
		(ii) Explain instruction	
			20403
	1,1	(iii) Interrupt latency	